

DESCRIPTION

The A25CM02 is electrically erasable programmable memory (EEPROM) organized as 262144 x 8 bits, accessed through the SPI bus.

The A25CM02 can operate with a supply range from 2.8V to 5.5V.

The A25CM02 offers an additional page, named the Identification Page (256 bytes). The Identification Page can be used to store sensitive application parameters which can be (later) permanently locked in Read-only mode.

The A25CM02 is available in SOP8 and CSP8 Packages.

ORDERING INFORMATION

Package Type		Part Number	
SOP8	M8	A25CM02M8R-YZ	
SPQ: 2,500/Reel	IVIO	A25CM02M8VR-YZ	
CSP8	0	A25CM02G8R-YZ	
SPQ: 3,000pcs/Reel	G8	A25CM02G8VR-YZ	
	Y= Spe	ed	
	2=2MHz		
	5=5MHZ		
	Z: Temperature:		
Note	A : -40°C to +85°C		
	B : -40°C to +105°C		
	C : -40	℃ to +125℃	
	V: Halo	ogen free Package	
	R: Tape & Reel		
AiT provides all RoHS	Complia	nt Products	

FEATURES

- Serial Peripheral Interface (SPI) data transfer protocol
- Memory array:
 - 2M bits (256 Kbytes) of EEPROM
 - Page size: 256 bytes
 - Additional Write lockable page
 - Extended Temperature Range
 - A : -40°C to +85°C
 - B : -40°C to +105°C
 - C : -40°C to +125°C
 - Single supply voltage and high speed:
 - A25CM02-2 2MHz (2.8V-5.5V)
 - A25CM02-5 5MHz (2.8V-5.5V)
- Random and sequential Read modes
- Write:
 - Write within 8 ms
 - Partial Page Writes Allowed
- Write Protect: quarter, half or whole memory array
- High-reliability
 - Endurance: 1 Million Write Cycles
 - Data Retention: 100 Years
- Enhanced ESD/Latch-up protection
 HBM 8000V



PIN DESCRIPTION

Vcc 8	HOLD SCK	SI 5	А	1 2 0	3 4 O		
A25CM02 SOP8			В		O CM02 SP8		
• 1 CS	2 SO WP	4 Vss	C D	0 0	0 0		
	SOP8, M8			CSP8	, G8		
	Top View			Тор \	/iew		
SOP8	CSP8	Symbol	Туре		Functions		
1	A3	CS	Ι	Chip S	Chip Select		
2	B4	SO	0	Serial	Data Out	put	
3	C4	WP	Ι	Write I	Protect		
4	D3	Vss	Р	Groun	d		
5	D2	SI	Ι	Serial	Data Inpu	ıt	
6	C1	SCK	Ι	Serial	Clock		
7	B2	HOLD	Ι	Hold			
8	A2	Vcc	Р	Power	Supply		

CSP8

Position	A	В	С	D
1	-	-	SCK	-
2	V _{CC}	HOLD	-	SI
3	CS	-	-	Vss
4	-	SO	WP	-



ABSOLUTE MAXIMUM RATINGS

Parameter	Rating	Unit
Storage Temperature	–65 to +150	°C
Voltage on any Pin with Respect to Ground *	–0.5 to +6.5	V
ESD (HBM)	8000	V

Stresses above may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated in the Electrical Characteristics are not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

*The DC input voltage on any pin should not be lower than -0.5 V or higher than V_{CC} + 0.5 V. During transitions, the voltage on any pin may overshoot to no less than -1.5 V or overshoot to no more than V_{CC} + 1.5 V, for periods of less than 20 ns.

RELIABILITY CHARACTERISTICS (1)

Parameter	Parameter Symbol Min.		Unit
Endurance	Nend (2)(3)	1000,000	Program/Erase Cycles
Data Retention	TDR	100	Years

(1) These parameters are tested initially and after a design or process change that affects the parameter according to appropriate AEC-Q100 and JEDEC test methods.

(2) Page Mode, V_{CC} = 5V, 25°C.

(3) The A25CM02 uses ECC (Error Correction Code) logic with 6 ECC bits to correct one bit error in 4 data bytes. Therefore, when a single byte has to be written, 4 bytes (including the ECC bits) are re-programmed. It is recommended to write by multiple of 4 bytes located at addresses 4N, 4(N+1), 4(N+2), 4(N+3), in order to benefit from the maximum number of write cycles.

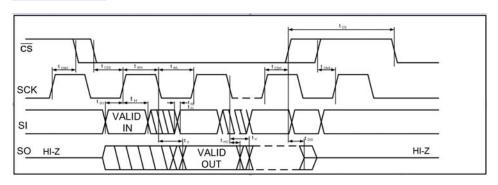
POWER-UP TIMING (1) (2)

Parameter	Symbol *	Min.	Unit
Power-up to Read / Write Operation	tpur, tpuw	0.1	ms

(1) This parameter is tested initially and after a design or process change that affects the parameter.

(2) t_{PUR} and t_{PUW} are the delays required from the time V_{CC} is stable until the specified operation can be initiated.

BUS TIMING





DC ELECTRICAL CHARACTERISTICS

V_{CC} = 2.8V to 5.5V, unless otherwise specified.

A25CM02-A	T _A =-40°C to +85°C	V _{CC} = +2.8V to +5.5V
A25CM02-B	T _A =-40°C to +105°C	
A25CM02-C	T _A =-40°C to +125°C	

Parameter	Symbol	Conditions	Min.	Max.	Unit
Supply Current (Read Mode)	I _{CCR}	Read, SO open 2.8 V < V _{CC} < 5.5 V	-	3	mA
Supply Current (Write Mode)	Iccw	Write, CS = V _{CC} 2.8 V < V _{CC} < 5.5 V	_	3	mA
Standby Current	I _{SB1} *	$V_{IN} = GND \text{ or } V_{CC},$ $\overline{CS} = V_{CC}, \overline{WP} = V_{CC},$ $\overline{HOLD} = V_{CC}, V_{CC} = 5.5V$	-	5	μA
Standby Current	Isb2*	$V_{IN} = GND \text{ or } V_{CC},$ $\overline{CS} = V_{CC}, \overline{WP} = GND,$ $\overline{HOLD} = GND, V_{CC} = 5.5V$	-	5	μA
Input Leakage Current	١L	V_{IN} = GND or V_{CC}	-	± 2	μA
Output Leakage Current	Ιιο	CS = Vcc, Vout = GND or Vcc	_	±2	μA
Input Low Voltage	VIL1	Vcc ≥ 2.8V	-0.45	0.3 Vcc	V
Input High Voltage	VIH1	V _{CC} ≥ 2.8 V	0.7 Vcc	Vcc+1	V
Output Low Voltage	V _{OL1}	V _{CC} ≥ 2.8 V, I _{OL} = 3.0 mA	-	0.4	V
Output High Voltage	V _{OH1}	V _{CC} ≥ 2.8 V, I _{OH} = −1.6 mA	0.8 V _{CC}	-	V

* When not driven, the WP and HOLD inputs are pulled up to V_{CC} internally. For noisy environments, when the pin is not used, it is recommended the WP and HOLD input to be tied to V_{CC}, either directly or through a resistor.



AC ELECTRICAL CHARACTERISTICS

 V_{CC} = 2.8V to 5.5V, unless otherwise specified. ⁽¹⁾

A25CM02-A	T _A =-40°C to +85°C	V _{CC} = +2.8V to +5.5V
A25CM02-B	T _A =-40°C to +105°C	
A25CM02-C	T _A =-40°C to +125°C	

Parameter	Symbol	Min.	Max.	Units
Clock Frequency	f _{scк}	DC	5	MHz
Data Setup Time	tsu	20		ns
Data Hold Time	tн	20		ns
SCK High Time	twн	75		ns
SCK Low Time	tw∟	75		ns
HOLD to Output Low Z	t _{LZ}		50	ns
Input Rise Time	t _{RI} ⁽²⁾		2	μs
Input Fall Time	t _{FI} ⁽²⁾		2	μs
HOLD Setup Time	t _{HD} 0			ns
HOLD Hold Time	tcp	10		ns
Output Valid from Clock Low	t∨		75	ns
Output Hold Time	t _{но}	0		ns
Output Disable Time	tois		50	ns
HOLD to Output High Z	tнz		100	ns
CS High Time	t _{cs}	80		ns
CS Setup Time	tcss	60		ns
CS Hold Time	tсsн	60		ns
CS Inactive Setup Time	t _{CNS}	60		ns
CS Inactive Hold Time	tсnн	60		ns
WP Setup Time	twps	20		ns
WP Hold Time	twpн	20		ns
Write Cycle Time	twc ⁽³⁾		8	ms

(1) AC Test Conditions:

Input Pulse Voltages: 0.3 V_{CC} to 0.7 V_{CC}

Input rise and fall times: ≤ 10 ns

Input and output reference voltages: 0.5 $V_{\mbox{\scriptsize CC}}$

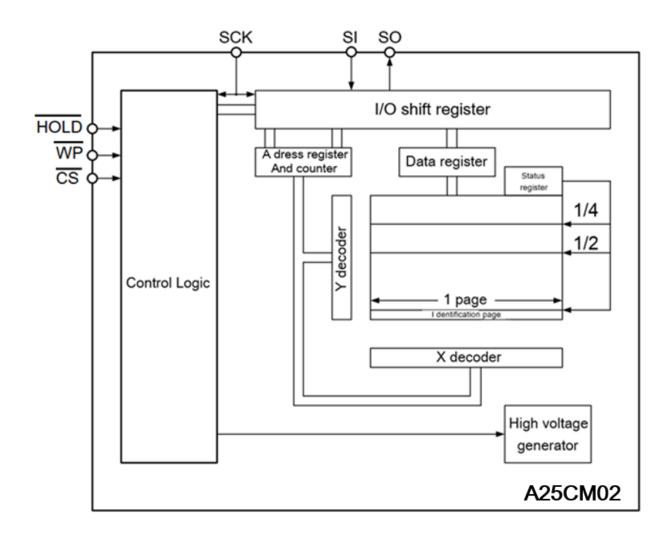
Output load: current source I_{OL} max/I_{OH} max; CL = 30 pF

(2) This parameter is tested initially and after a design or process change that affects the parameter.

(3) twc is the time from the rising edge of CS after a valid write sequence to the end of the internal write cycle.



BLOCK DIAGRAM





DETAILED INFORMATION

Serial Data Input (SI)

The SPI Serial data input (SI) is used to serially receive write instructions, addresses or data to the device on the rising edge of the Serial Clock (SCK) input pin.

Serial Data Output (SO)

The SPI Serial data output (SO) is used to read data or status from the device on the falling edge of CLK. Serial Clock (SCK): The SPI Serial Clock Input (S_{CK}) pin provides the timing for serial input and output operations.

Chip Select (CS)

The SPI Chip Select (\overline{CS}) pin enables and disables device operation. When (\overline{CS}) is high, the device is deselected and the Serial Data Output (SO) pins are at high impedance. When deselected, the devices power consumption will be at standby levels unless an internal write cycle is in progress. When (\overline{CS}) is brought low, the device will be selected, power consumption will increase to active levels and instructions can be written to and data read from the device. After power-up, (\overline{CS}) must transition from high to low before a new instruction will be accepted.

Hold (HOLD)

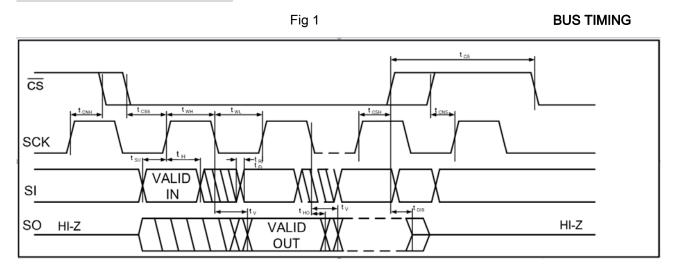
The **HOLD** pin allows the device to be paused while it is actively selected. When **HOLD** is brought low, while **CS** is low, the SO pin will be at high impedance and Signals on the S_I and S_{CK} pins will be ignored (don't care). When **HOLD** is brought high, device operation can resume. The **HOLD** function can be useful when multiple devices are sharing the same SPI signals. The **HOLD** pin is active low.

Write Protect (WP)

The Write Protect (\overline{WP}) pin is used in conjunction with the Status Register Write Disable (SRWD) Bit to prevent the Status Registers from being written. Write Protect (\overline{WP}) pin and Status Register Write Disable (SRWD) Bit enable the device to be put in the Hardware Protected mode (when Status Register Write Disable (SRWD) Bit is set to 1, and Write Protect (\overline{WP}) pin is driven low.



FUNCTIONAL DESCRIPTION



The A25CM02 features an additional Identification Page (256 bytes) which can be accessed for Read and Write operations when the IPL bit from the Status Register is set to "1". The user can also choose to make the Identification Page permanent write protected by setting the LIP bit from the Status Register (LIP="1").

	Table 1					
Instruction	Opcode	Operation				
WREN	0000 0110	Enable Write Operations				
WRDI	0000 0100	Disable Write Operations				
RDSR	0000 0101	Read Status Register				
WRSR	0000 0001	Write Status Register				
READ	0000 0011	Read Data from Memory				
WRITE	0000 0010	Write Data to Memory				
RDID	1000 0011	Read identification page				
WRID	1000 0010	Write identification page				
RDLS	1000 0011	Reads the identification page lock status				
LID	1000 0010	Locks the identification page in read-only mode				



1. Status Register

The Status Register, as shown in Table 2, contains a number of status and control bits.

Table 2							
7 6 5 4 3 2 1						0	
SRWD	0	0	0	BP1	BP0	WEL	READY

READY: The **READY** bit indicates whether the device is busy with a write operation. This bit is automatically set to 1 during an internal write cycle, and reset to 0 when the device is ready to accept commands. For the host, this bit is read only.

BP0, BP1: The BP0 and BP1 (Block Protect) bits determine which blocks are currently write protected. They are set by the user with the WRSR command and are non-volatile. The user is allowed to protect a quarter, one half or the entire memory, by setting these bits according to Table 3. The protected blocks then become read-only.

Table 3	
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Status Reg	Status Register Bits		Drotection
BP1	BP1	Array Address Protected	Protection
0	0	None	No Protection
0	1	30000h-3FFFFh	Quarter Array Protection
1	0	20000h-3FFFFh	Half Array Protection
1	1	00000h-3FFFFh	Full Array Protection

SRWD: The SRWD (Status Register Write Disable) bit acts as an enable for the WP pin. Hardware write protection is enabled when the WP pin is low and the SRWD bit is 1. This condition prevents writing to the status register and to the block protected sections of memory. While hardware write protection is active, only the non-block protected memory can be written. Hardware write protection is disabled when the WP pin is high or the SRWD bit is 0. The SRWD bit, WP pin and WEL bit combine to either permit or inhibit Write operations, as detailed in Table 4.

Table 4	Та		е	4
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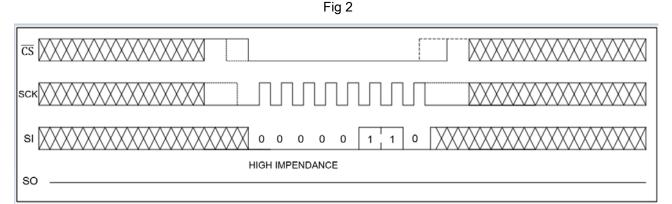
SRWD	WP	WEL	Protected Blocks	Unprotected Blocks	Status Register
0	Х	0	Protected	Protected	Protected
0	Х	1	Protected	Writable	Writable
1	Low	0	Protected	Protected	Protected
1	Low	1	Protected	Writable	Protected
Х	Hight	0	Protected	Protected	Protected
Х	Hight	1	Protected	Writable	Writable



2. Write Operations

The A25CM02 powers up into a write disable state. The device contains a Write Enable Latch (WEL) which must be set before attempting to write to the memory array or to the status register. In addition, the address of the memory location(s) to be written must be outside the protected area, as defined by BP0 and BP1 bits from the status register.

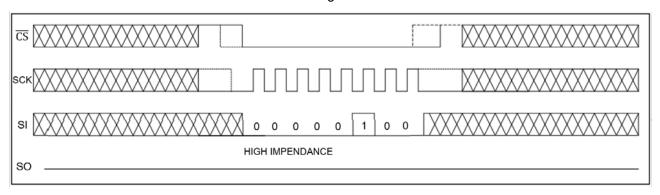
Write Enable and Write Disable : The internal Write Enable Latch and the corresponding Status Register WEL bit are set by sending the WREN instruction to the A25CM02. Care must be taken to take the \overline{CS} input high after the WREN instruction, as otherwise the Write Enable Latch will not be properly set. WREN timing is illustrated in Fig 2. The WREN instruction must be sent prior to any WRITE or WRSR instruction.



Note: Dashed Line =mode (1,1)

The internal write enable latch is reset by sending the WRDI instruction as shown in Fig 3. Disabling write operations by resetting the WEL bit, will protect the device against inadvertent writes.

Fig 3

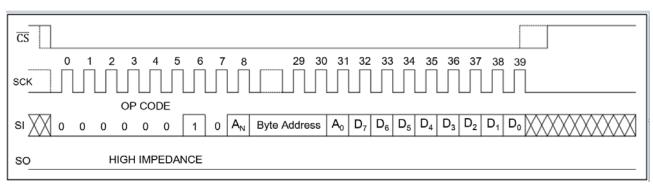


Note: Dashed Line =mode (1,1)



Byte Write: Once the WEL bit is set, the user may execute a write sequence, by sending a WRITE instruction, a 24-bit address and a data byte as shown in Fig 4. Only 17 significant address bits are used by the A25CM02. The rest are don't care bits, as shown in Table 5. Internal programming will start after the low to high \overline{CS} transition. During an internal write cycle, all commands, except for RDSR (Read Status Register) will be ignored. The **READY** bit will indicate if the internal write cycle is in progress (**READY** high), or the device is ready to accept commands (**READY** low).



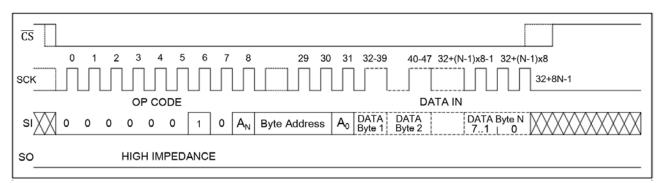


Please check the Byte Address Table 5.

Note: Dashed Line =mode (1,1)

Page Write: After sending the first data byte to the A25CM02, the host may continue sending data, up to a total of 256 bytes, according to timing shown in Fig 5. After each data byte, the lower order address bits are automatically incremented, while the higher order address bits (page address) remain unchanged. If during this process the end of page is exceeded, then loading will "roll over" to the first byte in the page, thus possibly overwriting previously loaded data. Following completion of the write cycle, the A25CM02 is automatically returned to the write disable state.



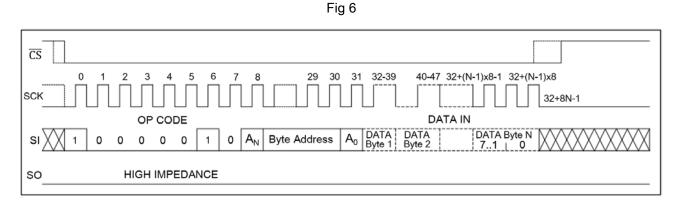


Please check the Byte Address Table 5.

Note: Dashed Line =mode (1,1)



Write Identification Page: The additional 256-byte Identification Page (IP) (256 bytes) is an additional page which can be written and (later) permanently locked in Read-only mode. Writing this page is achieved with the Write Identification Page instruction, according to timing shown in Fig 6. Address bit A10 must be 0, upper address bits are Don't Care, the lower address bits [A7:A0] address bits define the byte address inside the identification page. The byte address must not exceed the 256-byte page boundary.



Please check the Byte Address Table 5.

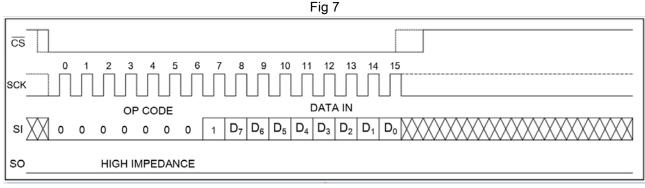
Note: Dashed Line =mode (1,1)

Table 5

Device	Address Significant Bits	Address Don't Care Bits	# Address Clock Pulses
Main Memory Array	A17 – A0	A23 – A18	24
Identification Page	A7 – A0	A23 – A8	24

Write Status Register (WRSR)

The Status Register is written by sending a WRSR instruction according to timing shown in Fig 7. Only bits 2, 3, 4, 5, 6 and 7 can be written using the WRSR command.



Note: Dashed Line =mode (1,1)



Lock Identification Page: The Lock ID instruction permanently locks the Identification Page in read-only mode. Before this instruction can be accepted, a Write Enable (WREN) instruction must have been executed. Lock Identification page is achieved with the Write Identification Page instruction, according to timing shown in Fig 8. Address bit A10 must be 1, all other address bits are Don't Care. The data bit1 must be"1", other bits don't care.

The instruction is discarded, and is not executed, under the following conditions:

- If a Write cycle is already in progress,
- If the Block Protect bits (BP1, BP0) = (1,1),
- If a rising edge on Chip Select (CS) happens outside of a byte boundary.

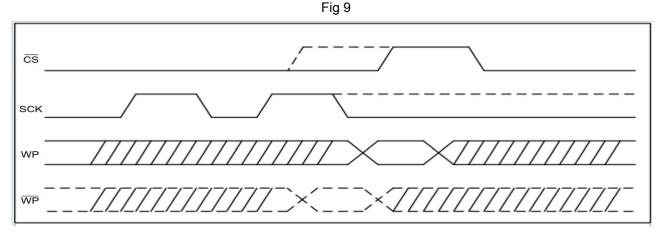
cs	
0 1 2 3 4 5 6 7 8 29 30 31 32 33 34 35 36 37	38 39
OP CODE DATA IN	
SI 1 0 0 0 1 0 A _N Byte Address A ₀ D ₇ D ₆ D ₅ D ₄ D ₃ D ₂	
SOHIGH IMPEDANCE	

Fig 8

Please check the Byte Address Table 5.

Note: Dashed Line =mode (1,1)

Write Protection: The Write Protect (WP) pin can be used to protect the Block Protect bits BP0 and BP1 against being inadvertently altered. When WP is low and the SRWD bit is set to "1", write operations to the Status Register are inhibited. WP going low while CS is still low will interrupt a write to the status register. If the internal write cycle has already been initiated, WP going low will have no effect on any write operation to the Status Register. The WP pin function is blocked when the SRWD bit is set to "0". The WP input timing is shown in Fig 9.

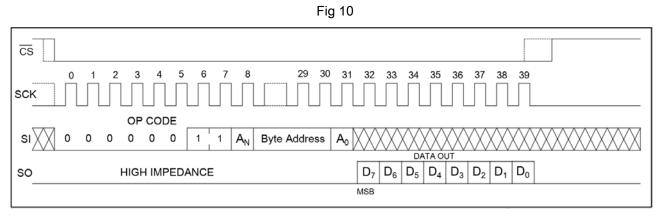


Note: Dashed Line =mode (1,1)



3. Read Operations

Read from Memory Array: To read from memory, the host sends a READ instruction followed by a 24-bit address (see Table 4 for the number of significant address bits). After receiving the last address bit, the A25CM02 will respond by shifting out data on the SO pin (as shown in Fig 10). Sequentially stored data can be read out by simply continuing to run the clock. The internal address pointer is automatically incremented to the next higher address as data is shifted out. After reaching the highest memory address, the address counter "rolls over" to the lowest memory address, and the read cycle can be continued indefinitely. The read operation is terminated by taking \overline{CS} high.

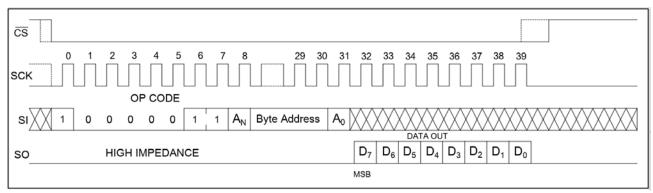


Please check the Byte Address Table 5.

Note: Dashed Line =mode (1,1)

Read Identification Page Lock Status: To read Identification Page Lock status, the host simply sends a RDLS command, according to timing shown in Fig 11. The address bit A10 must be 1, all other address bits are Don't Care. The Lock bit is the bit0 of the byte read on the SO pin. It is at "1" when the lock is active and at "0" when the lock is not active. The same date byte may be read at any time, including during an internal write cycle.

Fig 11



Please check the Byte Address Table 5.

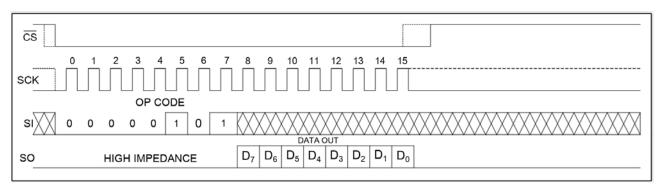
(Note: Dashed Line =mode (1,1)



Read Status Register (RDSR)

To read the status register, the host simply sends a RDSR command. After receiving the last bit of the command, the A25CM02 will shift out the contents of the status register on the SO pin (Fig 12). The status register may be read at any time, including during an internal write cycle.

Fig 12



(Note: Dashed Line =mode (1,1)

4. Hold Operation

The **HOLD** input can be used to pause communication between host and A25CM02. To pause, **HOLD** must be taken low while SCK is low (Figure 10). During the hold condition the device must remain selected (CSlow). During the pause, the data output pin (SO) is tri-stated (high impedance) and SI transitions are ignored. To resume communication, **HOLD** must be taken high while SCK is low.

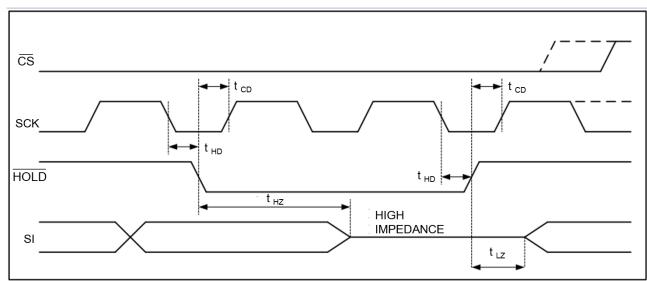


Fig 13

(Note: Dashed Line =mode (1,1)



5. Design Considerations

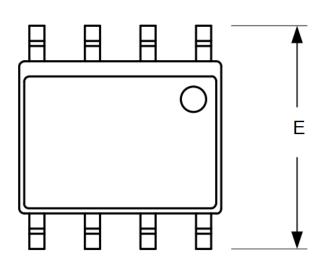
The A25CM02 incorporates Power–On Reset (POR) circuitry which protects the internal logic against powering up in the wrong state. The A25CM02 will power up into Standby mode after VCC exceeds the POR trigger level and will power down into Reset mode when VCC drops below the POR trigger level. This bi–directional POR behavior protects the device against 'brown–out' failure following a temporary loss of power. The A25CM02 powers up in a write disable state and in a low power standby mode. A WREN instruction must be issued prior to any writes to the device.

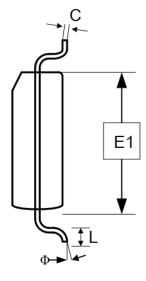
After power up, the \overline{CS} pin must be brought low to enter a ready state and receive an instruction. After a successful byte/page write or status register write, the device goes into a write disable mode. The \overline{CS} input must be set high after the proper number of clock cycles to start the internal write cycle. Access to the memory array during an internal write cycle is ignored and programming is continued. Any invalid op-code will be ignored and the serial output pin (SO) will remain in the high impedance state.

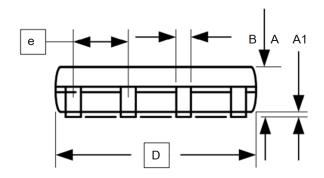


PACKAGE INFORMATION

Dimension in SOP8 (Unit: mm)



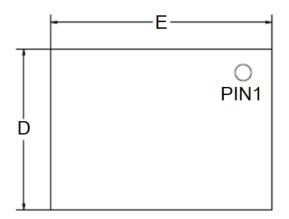




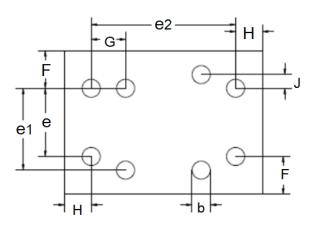
Symbol	Min.	Max.	
А	1.350	1.750	
A1	0.100	0.230	
В	0.390	0.480	
С	0.210	0.260	
D	4.700	5.100	
E1	3.700	4.100	
E	5.800	6.200	
е	1.270 BSC		
L	0.500	0.800	
Φ	0 °	8°	



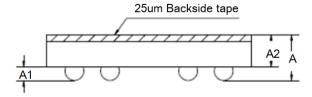
Dimension in CSP8 (Unit: mm)



TOP VIEW (MARK SIDE)



BOTTOM VIEW (BALL SIDE)



Symbol	Min	Max	
А	0.490	0.590	
A1	0.165	0.215	
A2	0.325	0.375	
D	2.080	2.120	
e 1	1.200 BSC		
E	2.860	2.900	
e 2	2.100 BSC		
b	0.2400 0.3000		
G	0.500 BSC		
е	1.000 BSC		
Н	0.390 REF		
F	0.550 REF		
J	0.200 REF		



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